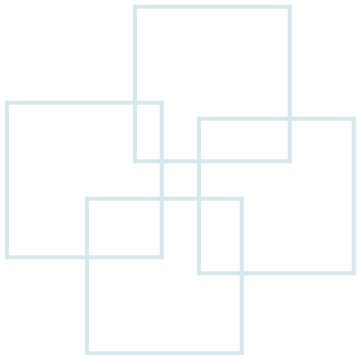


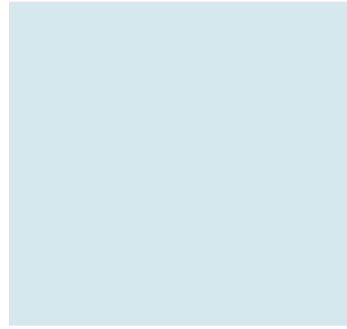
# Topic 8: Approximation Algorithms



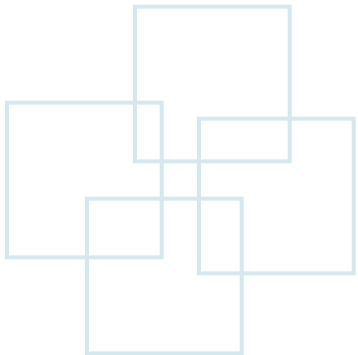


# Outline

- Overview
- The Vertex-cover problem



# Overview





# NP-Complete Problems in Practice

- NP-complete problems are too important to abandon.
- Even if a problem is NP-complete, there may be hope.
- We have at least three ways to get around NP-completeness.
  - 1. If the actual inputs are small, an algorithm with exponential running time may be perfectly satisfactory.
  - 2. We may be able to isolate important special cases that we can solve in polynomial time.
  - 3. we might come up with approaches to find *near-optimal solutions* in polynomial time (either in the *worst case* or the *expected case*).
    - We call an algorithm that returns near-optimal solutions an *approximation algorithm*.



# Performance Ratios

- An algorithm for a problem has an **approximation ratio** of  $\rho(n)$  if, for any input of size  $n$ , the cost  $C$  of the solution produced by the algorithm is within a factor of  $\rho(n)$  of the cost  $C^*$  of an optimal solution:

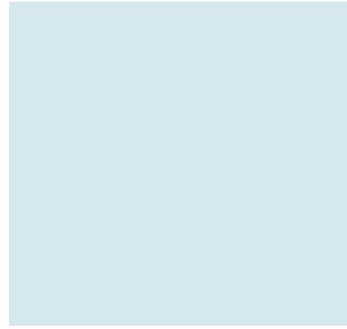
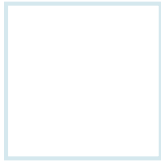
$$\max \left( \frac{C}{C^*}, \frac{C^*}{C} \right) \leq \rho(n)$$

- If an algorithm achieves an approximation ratio of  $\rho(n)$ , we call it a  **$\rho(n)$ -approximation algorithm**.
  - For a maximization problem,  $0 < C \leq C^*$  and ratio =  $C^*/C$
  - For a minimization problem,  $0 < C^* \leq C$  and ratio =  $C/C^*$
- The approximation ratio of an approximation algorithm is **never less than 1**.

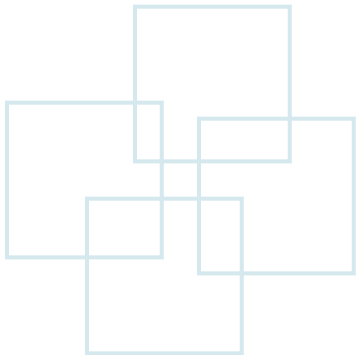


# Approximation Scheme

- An **approximation scheme** for an optimization problem:
  - An approximation algorithm that takes as input not only an instance of the problem, but also a value  $\varepsilon > 0$  such that for any fixed  $\varepsilon$ , the scheme is a  **$(1+\varepsilon)$ -approximation algorithm**.
    - **Polynomial-time approximation scheme (PTAS)**
      - If for any fixed  $\varepsilon > 0$ , the scheme runs in time polynomial in the size  $n$  of its input instance. E.g.,  $O(n^{1/\varepsilon})$ ,  $O(n^{2/\varepsilon})$
    - **Fully Polynomial-time approximation scheme (FPTAS)**
      - If the scheme is an approximation scheme and its running time is polynomial in both  $1/\varepsilon$  and the size  $n$  of the input instance. E.g.,  $O((1/\varepsilon)n)$ ,  $O(1/\varepsilon)^2 n^3$ .
      - Any constant-factor decrease in  $\varepsilon$  comes with a corresponding constant-factor increase in the running time.



# The Vertex-Cover Problem





# Vertex-Cover Problem

- A **vertex cover** of an undirected graph  $G = (V, E)$  is a subset  $V' \subseteq V$  such that if  $(u, v)$  is an edge of  $G$ , then either  $u \in V'$  or  $v \in V'$  (or both).
- The **size** of a vertex cover is the number of vertices in it.
- The **vertex-cover problem** is to find a vertex cover of minimum size in a given undirected graph. We call such a vertex cover an **optimal vertex cover**.
- This problem is the **optimization version** of an NP-complete decision problem.





# A 2-Approximation Algorithm

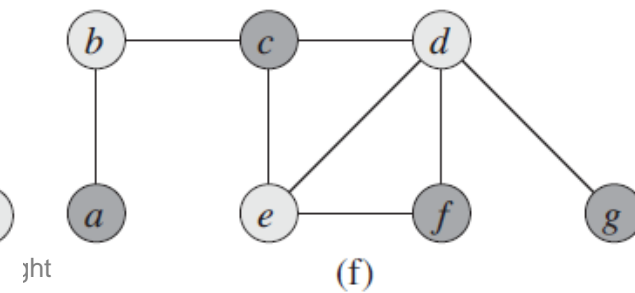
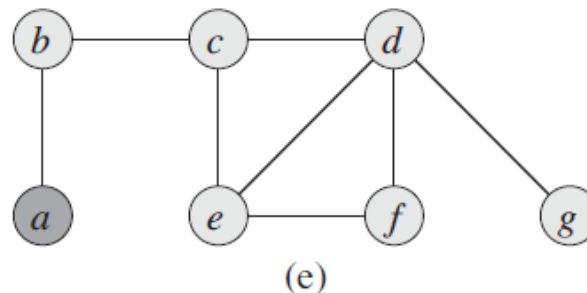
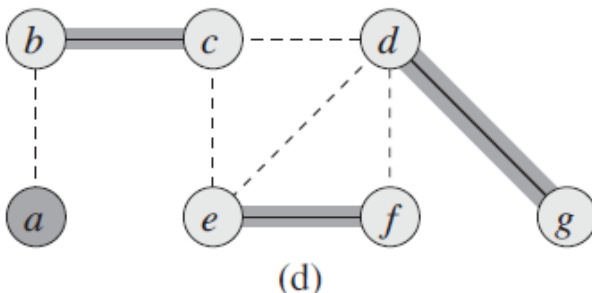
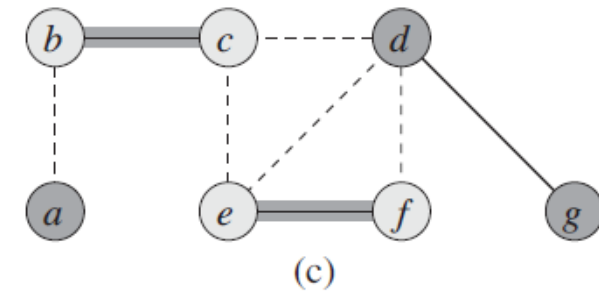
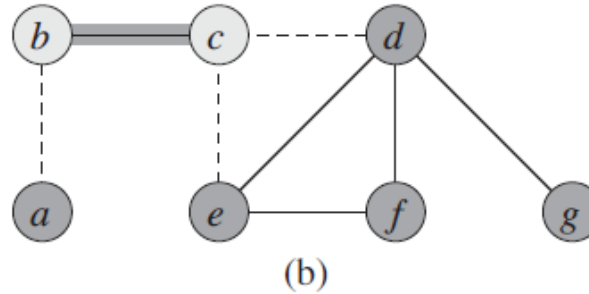
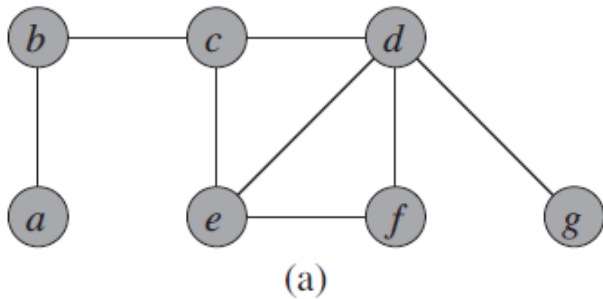
Using *adjacency lists* to represent  $E'$ , the running time of this algorithm is  $O(V+E)$ .

## APPROX-VERTEX-COVER( $G$ )

```

1   $C = \emptyset$ 
2   $E' = G.E$ 
3  while  $E' \neq \emptyset$ 
4      let  $(u, v)$  be an arbitrary edge of  $E'$ 
5       $C = C \cup \{u, v\}$ 
6      remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7  return  $C$ 

```





# A 2-Approximation Algorithm (Cont.)

## • Theorem 35.1

- APPROX-VERTEX-COVER is a polynomial-time 2-approximation algorithm.

## • Proof

- APPROX-VERTEX-COVER runs in polynomial time:  $O(V+E)$
- Let  $A$  denote the set of edges that line 4 of APPROX-VERTEX-COVER picked.
  - In order to cover the edges in  $A$ , any vertex cover (including an optimal cover  $C^*$ ) must include at least one endpoint of each edge in  $A$ .
  - No two edges in  $A$  share an endpoint, since once an edge is picked in line 4, all other edges that are incident on its endpoints are deleted from  $E'$  in line 6.  $\rightarrow |C^*| \geq |A|$
- Each execution of line 4 picks an edge for which neither of its endpoints is already in  $C$ .  $\rightarrow |C| = 2|A|$
- Therefore,  $|C| = 2|A| \leq 2|C^*|$

APPROX-VERTEX-COVER ( $G$ )

```

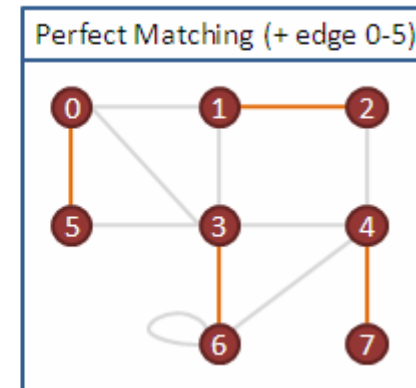
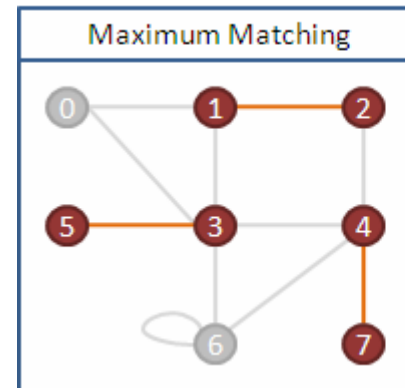
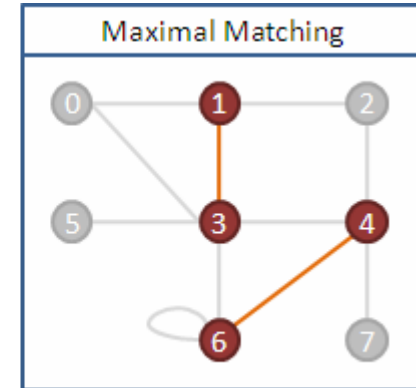
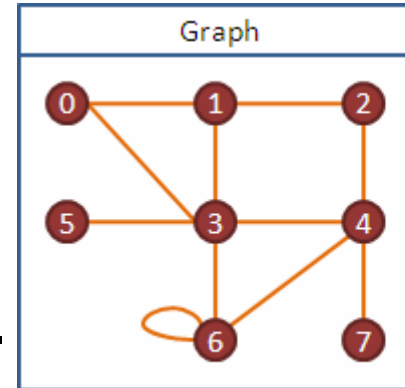
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```



# A 2-Approximation Algorithm (Cont.)

- How to prove without knowing the optimal vertex cover?  
→ Rely on the **lower bound**.
- The set **A** of edges is a a **maximal matching** that is a **lower bound** on the size of an optimal vertex cover.



maximal matching: a matching that is not a proper subset of any other matching  
 maximum matching : A matching that contains the largest possible number of edges.  
     Also a maximal matching ◦  
 perfect matching : A matching that matches all vertices of the graph. Also a maximum matching